# PROTORQ<sup>™</sup> 4960B SERIES HUBBELL INDUSTRIAL DRIVES FOR BRIDGE CONTROL

### **AC Drives for Lift Bridge Applications**

Hubbell Protorq<sup>™</sup> Series controls bridges that operate in the classifications of: Swing, Bascule and Vertical Lift.

### Rated:

208-240 VAC, 4.4 to 260A (0.75 to 150 HP) 380-500 VAC, 1.7 to 1274A (0.75 to 1000 HP) 525-690 VAC, 6.1 to 2421A (5 to 2500 HP)

Eliminating the need for an external PLC, the program incorporates all the functions commonly required in lift bridge applications and enables stepless speed and torque control.

A key feature of the Hubbell Protorq™ industrial drive is its motor control platform, direct torque control (DTC). DTC enables the drive to achieve full torque at zero speed with or without the need for a encoder feedback. In addition, the torque response of the drive is fast which means the bridge can react quickly to changes in movement commands. High torque levels can be reached, making the drive ideal for lifting operations. DTC delivers enhanced operational safety and accurate slow speed control.

Hubbell Protorq<sup>™</sup> industrial drives' built-in brake choppers connect the DC bus voltage to an external dynamic breaking resistor, where the braking energy is converted to heat.

Low harmonic drives help to maintain power supply quality and meet the strictest harmonic standards without any need for filtering equipment.

The drive can work in either standalone mode or as a master follower.







### **Optional Regenerative Drive Solutions**

Regenerative drives can recover energy from a process and feed it back into the network, thus saving energy. This single drive is a compact and complete regenerative drive solutions, with everything needed for a regenerative operation.

With regenerative functionality, the braking energy of the motor is returned back to the drive and distributed forward to the supply network. No need for external dynamic breaking resistor.

### **Removable Memory Unit**

The removable memory unit stores the software that includes user settings, parameter settings and motor data. Situated on the control unit, the memory unit can easily be removed for maintenance, firmware updates or replacement purposes. This common type of memory unit is used throughout the 4960B Series.



System parameters and motor data can also be uploaded to the HMI. The HMI can be removed and reinstalled in a new drive with the same system parameters.



### **Flexible Control Platform**

The Hubbell Protorq<sup>™</sup> firmware offers flexible interfaces for different types of analog, digital or fieldbus systems, enabling a wide range of connectivity for start, stop and reference change signals.

Analog Signal: 0-10 VDC, 4-20mA, ±10 VDC

Network communication modules available: Profibus, Profinet, CANopen, DeviceNet, Ethernet/IP, Modbus RTU, Powerlink and ControlNet.

### **Mechanical Brake Control & Torque Memory**

The bridge control program features an integrated brake control logic that utilizes torque memory and premagnetizing to open and close the mechanical brake safely and reliably. The drive can generate full torque on the motor shaft before the brake is released. In addition, brake status feedback signals improve the safety when a start or stop command is given.

### **Adaptive Programming**

Function block programming - included as standard - is like having a small PLC inside the drive. Adaptive programming, as it is also called, enables the user to integrate external control logic or create new functions, so the program can be customized quickly and easily.

### **Safety Control**

The 'slow down' safety control function limits the speed to a preset level in critical zones. High and low limit sensors stop the drive at the end positions. The 'fast stop' safety control function is used in emergency situations.

### **Speed Monitor and Speed Matching**

The speed monitor function ensures that the bridge motor speed remains within safe limits to prevent over speed. The speed matching function continuously compares the speed reference and the actual motor shaft speed to detect any possible difference. One of these functions will stop the motor immediately if a fault should occur in the operation of the motor.

### **Retrofit Older Wound Rotor Motors**

Hubbell 4960 Drive circuit incorporates a special dv/dt filter that allows the older existing motors to be used with the new drives. No need for costly motor replacement.



### **System Check**

The bridge system check function includes both electrical and mechanical checks. Torque proving ensures that the drive and motor are able to produce torque and that the mechanical brake does not slip before the drive releases the brake and starts operating the bridge.



### **Built-in STO (Safe Torque Off)**

Safe Torque Off is a function that prevents the drive from generating torque in the motor. It ensures that no torque generating energy continues to act on the motor and that the motor cannot be re-started until the STO is removed. What this means is that once the Safe Torque Off is activated the motor will not turn after it has come to a stop.

One of the major advantages compared to normal safety practices, both in terms of reduced cost and simplicity is the elimination of the need for input contactors or separate safety relays. Fewer components mean less effort in wiring and servicing. In addition electronic switching times are significantly quicker than electromechanical devices such as contactors or relays.

Certified SIL 3 / PL e safety rating and complies with EN/ IEC 61800-5-2 which is the standard that defines the Safe Torque Off feature.

Finally, it is important to remember that Safe Torque Off DOES NOT provide electrical isolation. The motor must be electrically isolated by cutting the supply to the drive and by local isolation to the motor before any access to the motor power connections.

### Flange Mounted Drive Kit

Flange mounted drive kits allow the heat sink to be external of the drive cabinet reducing the possible need for air conditioning in higher ambient applications. Instead of producing heat internal of the cabinet, it is moved to the exterior of the drive cabinet. Bridge drives can be rated to 55°C. Higher ambients and higher duty cycles will require flange kit and or air conditioning (Consult factory).

# **Color Coded Terminal Blocks**

Color coded terminal blocks allow for easy connection without incorrectly hooking up to the wrong input/outputs terminal points. Also, there is a barrier between the power connections (T1, T2, T3) on the bottom of the drive and the color coded control terminal blocks.



### I/O Hookup Diagram:

	YPOW	External p	oweringst
	1	+24VI	A STATE OF THE STA
	2	GND	24 V DC, 2 A
	XAI	Reference	voltage and analog inputs
		+VREF	10 V DC, RL 110 kohm
	2	-VREF	-10 V DC, R <sub>L</sub> 110 kohm
A 1 1:1 4:1	3	AGND	Ground
1 / 1 / 1	4	Al1+	Speed reference
J !	- 5	Al1-	0(2)10 V, R <sub>In</sub> > 200 kohm
, 产书	6	Al2+	By default not in use.
	7	Al2-	0(4)20 mA, R <sub>in</sub> > 100 ohm
	XAO	Analog ou	tputs
	1	AO1	Motor speed rpm
	2	AGND	020 mA, R <sub>L</sub> < 500 ohm
	3	AO2	Motor current
	4	AGND	020 mA, R <sub>L</sub> < 500 ohm
	XD2D	Drive-to-d	rive link
	1	В	
	2	A	Drive-to-drive link
	3	BGND	- 10 H
Darley and the dark	XRO1, X	KRO2, XRO3 Relay outputs	
Brake contactor	1	NC	
	2	COM	250 V AC / 30 V DC Brake open cmd
	3	NO	2A
	1	NC	
	2	COM	250 V AC / 30 V DC Running
Ext. Brake circuit	3	NO	2A
	1	NC	<b>-</b>
NA COMBINED TO THE	2	COM	250 V AC / 30 V DC Fault-1
Aux. Contact of	3	NO	2A
main contactor	XD24	Digital inte	
	1	DIIL	Power acknowledge (20.212) & Run enable (20.12)
0	2	+24VD	+24 V DC 200 mA
-	3	DICOM	Digital input ground
	4	+24VD	+24 V DC 200 mA
	5 XDIO		Digital input/output ground
	ADIO	Digital inp	the state of the s
	2	DIO1	Output: Ready
	XDI	DIO2	Output: Running
	ADI	Digital inp	Start forward (=Positive speed =Lifting load)
/	2	DI2	Start forward (=Positive speed =Lifting load)  Start reverse (=Negative speed= Lowering load)
	3	DI3	Brake ackn, see par.:44.07 Brake ackn.selection
	4	DI3	Drane dening see paint-107 brane deninselection
	5	DI5	
	6	DIS	
	100000000000000000000000000000000000000		ue off circuits must be closed for the drive to start. See
	XSTO	Hardware manual of drive.	
_			ions connection
X13 Control panel connection X205 Memory unit connection			





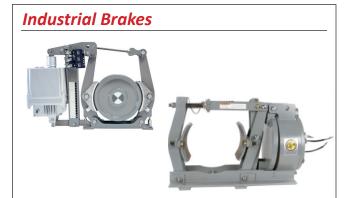






### **Radio Controls**





## **Cable Management Systems**





### **Contactors**





### **Magnet Controllers**









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