

TX5921/TX5922/TX5923 INSERTION VORTEX GAS FLOW SENSOR



Ex ia GROUP I M1 **GROUP II 1G** INTRINSICALLY SAFE

TUNNELS PIPELINES ٠ **ROADWAYS** • VENTILATION DUCTS • MINING •

PROCESS **INDUSTRIES**







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1 PRINCIPAL OPERATING FEATURES



The vortex flow velocity sensing system provides high accuracy, flow measurement free from drift and

mechanical deterioration.

As the stream of gas passes through the sensing head, vortices are generated by a transverse strut or 'Bluff

Body' positioned in the flow path. The vortex frequency is proportional to the flow velocity and this frequency is detected by an ultrasound beam accurately located downstream of the strut.

This information is processed by a specially designed software programme to provide user configurable

information display and a conditioned output signal.

- •Programmable information display for zero, span, signal offset, volumetric calculations, engineering units, turndown, damping, display suppression, fault mode, contrast, signal clamp.
- •Language display text options.
- •Keycode software security protection.
- •Simple pushbutton scaling to match on-site parameters. Signal offset, elevated zero, etc.
- •Sensing probe has standardised output for simple servicing without the need for a calibrated wind tunnel.
- •Output signal versions: 4...20 mA 0.4 ...2 V 5...15 Hz.
- •Rangeable velocity from 0.5 m...30 m/sec.
- •High pressure versions up to 20 bar.
- •Stainless steel sensing probe or special version with PTFE protective coating.
- •Non-standard sensing probe length for specific applications. •Non standard cable length on remote connected version for specific applications.
 - •Intrinsically Safe version for use in Group I and Group II hazardous areas.
 - •Automatic self test function.



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2 APPLICATION



Flow velocity measurement or volumetric measurement of air, gases and vapours in pipes, ducts and open areas.

- •Ventilation systems.
- Cooling systems.
- •Plant protection.
- •High accuracy transfer metering.

Environmental control and

monitoring. •Roadway and tunnel ventilation.



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•Versions with an integral sensor or a remote mounted sensor with a choice of adjustable mounting bush or

flange fittings for pipelines and ducts.

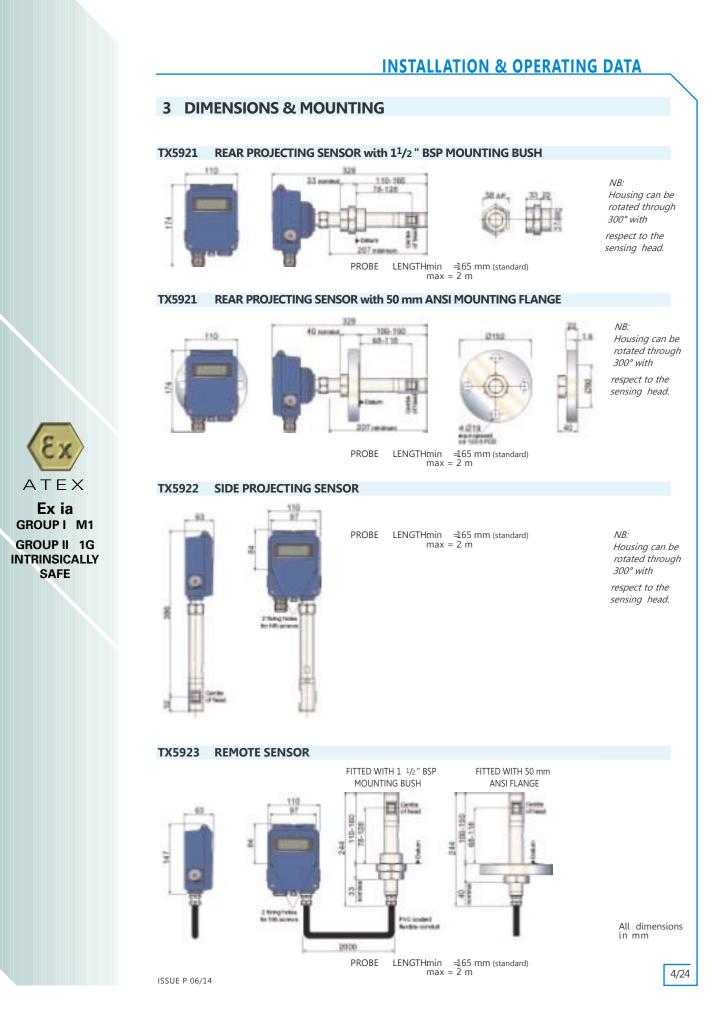
N.B. High pressure versions above 2bar, are fitted with a WELDED bush or flange to specific design information.





•Versions with side projecting sensor used mainly for back mounting in open area applications (eg. tunnels and roadways).







INSTALLATION & OPERATING DATA 4 TECHNICAL DETAILS 4.1 Specification TX5921 TX5922 TX5923 **REAR PROJECTING** SIDE PROJECTING **REMOTE SENSOR** SENSOR SENSOR Rangeable from 0.5 to 5 m/s up to 0.5 to 30 m/s linear flow velocity. Flow Measuring Range Accuracy ±2% characterised to the sensing element (within 12.5° rotation of flow axis). Linearity ±1% (within 12.5° rotation of flow axis). Housing Temperature -15 to +50°C. Sensor Temperature -15 to 150°C (200°C available to specification). Humidity 0 to 95% non condensing. **Protection Classification** Dust and waterproof to IP66. Stainless steel reinforced Stainless steel reinforced polymide 6. Housing Material polymide 6. 2 m – 3 core cable with PVC coated flexible conduit protection to the sensor. (Cable lengths up to 10 m can be supplied specification). Sensor Material Stainless steel (PTFE coated versions available to specification). Sensor Static Pressure 20 bar (limited to 2 bar max with standard mounting accessories). • 1¹/2" BSP mounting bush. Process Fitting Wall mounting. • 1¹/2" BSP mounting bush. 50 mm ANSI Flange. 50 mm ANSI Flange. (also available with (also available with welded process fittings for welded process fittings for high pressure applications high pressure applications to specification). to specification). Cable Entry 2 x M20. **Electrical Connections** 4 mm barrier/clamp terminals. Nett Weight 1.5 kg. 2.5 kg. 1.5 kg. Information Display 17 character dot matrix alpha numeric LCD Operation Microprocessor controlled with non-volatile data retention. Menu System • Programming of Span and Zero • On-site scaling • Signal offset • Failure mode **Keycode Protection** • Turndown • Volumetric Calculation • Engineering units • Signal damping • Display contrast • Display suppression • Signal fix. English Master Reset Text language: German French Spanish



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4 TECHNICAL DETAILS continued

4.2 Electrical Details

GENERAL PURPOSE APPLICATIONS

Output Signal:	420 mA
Max. Load:	600 ohms at 24 V dc
Power Supply:	1030 V dc
Max. Current:	40 mA

GROUP II APPLICATIONS

Output Signal:	420 mA	
Max. Load:	600 ohms at 24 V dc	(Ex)
Power Supply:	1030 V dc	GROUP II
Max. Current:	40 mA	Ex ia IIC T4 Ga

GROUP I APPLICATIONS

Output Signal:	420 mA	420 mA 0.42 V 515 Hz		
Max. Load:	300 ohms at 12 V dc	10K ohms at 12 V dc	Opto isolated 2 mA max	. (Ex)
Power Supply:	6.516.5 V dc			
Max. Current:	40 mA	15 mA	30 mA	Ex ia I Ma

CE Designed to comply with the requirements of the EC directive on:ATEX directive 94/9/EEC EMC directive 2004/108/EEC



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15 Hz

5 INSTALLATION

- 5.1 Conformity Check (Refer to Test Certificate provided with the sensor).
 - Does the output signal of the sensor concur with the input requirement of the monitoring equipment being used?



• Is the correct supply voltage available for the sensor?



• Is the velocity operating range of the system within the stated measuring range of the sensor? (0...30 m/sec).



• Is the maximum static pressure of the system within the stated pressure rating of the sensor?



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• Is the temperature variation range of the process medium within the stated temperature range of the sensor?

• Hazardous area classification?

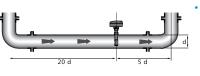
STANDARD OPTIONS AVAILABLE FOR INSERTION VORTEX GAS FLOW SENSORS

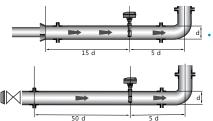
					output sigi	VAL	
TX5921	VORTEX GAS FLOW SENSOR/TRANSMITTER	Ex Group I	(01)	420 mA 0.42 V	(12) (11)	• 1 ¹ /2 " BSP Bush (22)	
	Rear Projecting Sensor.	- 6	Ex Group II	(02)	515 Hz 420 mA	(13)	• 50 mm ANSI Flange
	đ	đ	General Purpo	. ,	420 mA		(21)
TX5922	VORTEX GAS FLOW	0	Ex Group I	(01)	420 mA	(12)	
	SENSOR/TRANSMITTER				0.42 V	(11)	
	Side Projecting Sensor.	10			515 Hz	(13)	 Wall Mounting
			Ex Group II	(02)	420 mA		
		General Purpo	se (03)	420 mA			
TX5923	Vortex GAS Flow		Ex Group I	(01)	420 mA	(12)	
	SENSOR/TRANSMITTER				0.42 V	(11)	• 1 ¹ /2 " BSP Bush(22)
	Remote Sensor.	10.00			515 Hz	(13)	
	Remote Sensol.		Ex Group II	(02)	420 mA		• 50 mm ANSI Flange
			General Purpo	se (03)	420 mA		(21)



5 INSTALLATION continued

5.2 **Fitting in Pipes and Ducts**





• To attain the best accuracy of response, select a position that is at least twenty pipe diameters down-stream from bends or

obstructions and approximately five pipe diameters from down-stream intrusions.

Similarly, the sensor should be mounted at least fifteen pipe diameters from a pipe reducer and fifty pipe diameters from

If this is not possible then the installation of a standard flow straightener will improve performance.



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• Fit a corresponding threaded boss or flange at the monitoring point and install the sensor, ensuring a gas tight



N.B. High pressure versions, above 2 bar, will be supplied with a welded bush or flange and will

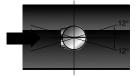
require dedicated process fittings.













- Release the clamping ring on the mounting bush or flange.
- The centre of the flow path of the sensing head should be



Ensure that pressurised systems have been completely vented before installation or removal of the sensor.

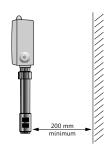
- Position the sensing head with the smaller opening facing the flow, within a rotational deviation of nomore than 12° from the axis of flow.
- Tighten the clamping ring with moderate force.
- Avoid fitting the sensor at 'Low points' in pipework structures to prevent the sensing head from being affected by large

accumulations of moisture



5 INSTALLATION continued

5.3 Fitting in Roadways & Tunnels (open area).



• To attain the best accuracy of response select a position away from adjacent structures and mount the sensor at

least 200 mm

- Using a rolex Pipe Mounting Bracket TX9200.11)
- Version TX5922 with a side projecting sensor can be mounted onto a suitable support using the mounting holes.



• Alternatively use a standard mounting bush or flange for fitting to a suitable bracket.

5.4 **Orientation of the Housing.**





The housing of the sensor can be turned to any position about the axis of the sensing probe and locked in position

for the preferred mounting attitude or cable routing access.

- Release the locking ring (CCW) as far as it will go.
- Rotate the sensing probe or the sensor housing to the desired position. (Rotation is limited to approximately 360° so do not force the limit stops).



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5 INSTALLATION continued

5.5 Precautions.

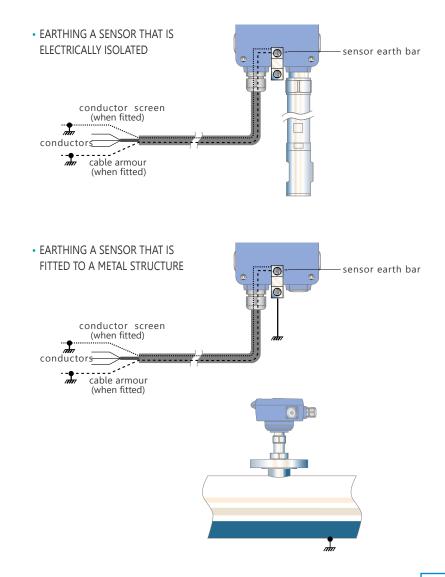
• Care should be taken, in the choice of installation, to ensure that vapour in the gas stream cannot condense onto the sensing head. This may cause an

intermittent fault or temporary loss of signal.

Operation can be restored by carefully cleaning the sensing head (Section 11.4).

5.6 Earthing.

• Take care to ensure correct earthing procedures during installation. Because of its high response sensitivity, the TX5920 can be affected by earth borne electrical interference where associated metal structures have not been properly earthed.

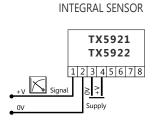


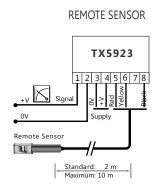


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6 CONNECTIONS



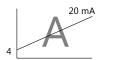




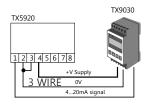
Ensure that the process pipe or duct work is correctly earthed in accordance with local regulations. Inadequate earthing may adversely affect the operation of the

sensor. Where the unit is installed in an electrically noisy environment, it may be necessary to bond the sensor metalwork to a local secure earthpoint (Section 5.6).

6.1 4...20 mA Output Signal.

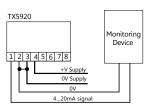


The output signal from terminals 1 and 2 is a conventional 4...20 mA current regulated signal loop.



Due to the power requirement of the processing stages of the sensor, a separate power supply feed is also required.

This can be sourced from the monitoring equipment



(eg. TX9031 Trip Amplifier or a TX9044 Programmable Sensor Controller) or from a separate power supply.

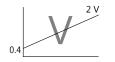


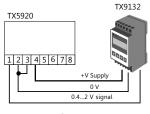
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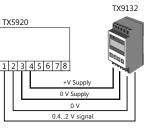
6 **CONNECTIONS** continued

6.2 0.4...2 V Output Signal.





3 WIRE



4 WIRE

A low impedance two-wire voltage output signal requiring a separate power supply to the sensor. This can be derived from a Trip Amplifier or Programmable Sensor Controller, when one of those is used as the monitoring instrument.

This connection configuration works well up to about 100 metres distance between the sensor and the monitoring equipment.

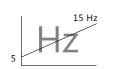
Both the signal and the power supply to the sensor are being carried in the common 0 V conductor so at some point – influenced by the length of the cable and the resistance of the cable cores – the current flowing in the 0 V conductor will

impose an unacceptable voltage error onto the signal.

This effect can be reduced on long distance connections by increasing the size of the cable cores, or even better, running a

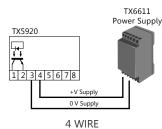
separate 0 V conductor to power the sensor.

6.3 5...15 Hz Output Signal.



A square wave, frequency variable, output that is proportional to the measured value. The output device is an uncommitted

NPN transistor.



Output:	515 Hz.	(zero = 5 Hz).	(span = 15 Hz).
Maximum Voltage:	15.4 V.		
Maximum Current:	2 mA.		
Min. Pulse Rise Time:	5 V/ms.		

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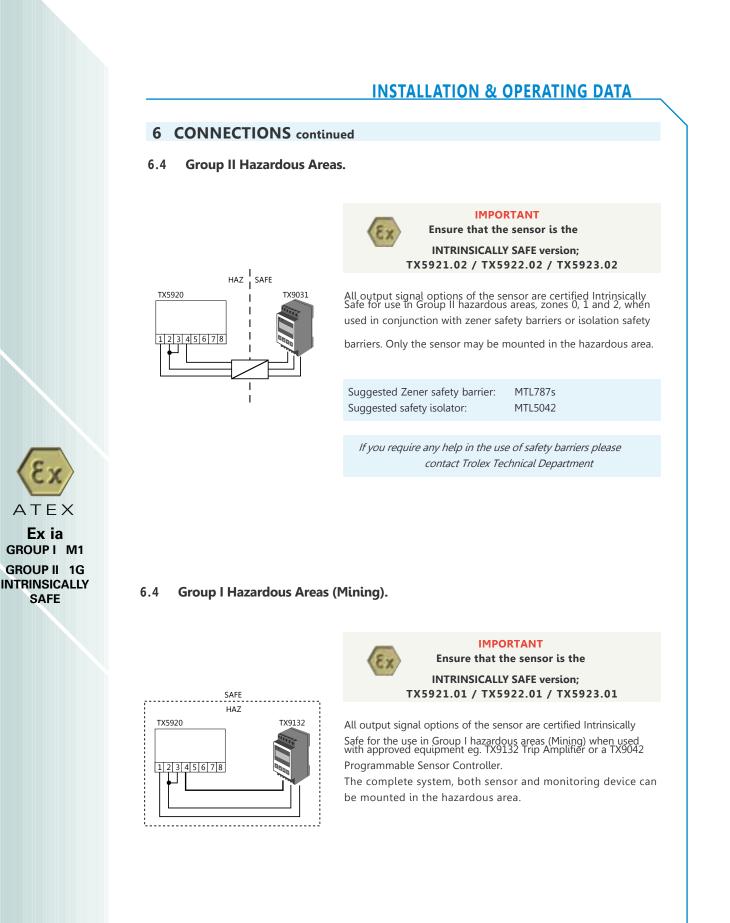
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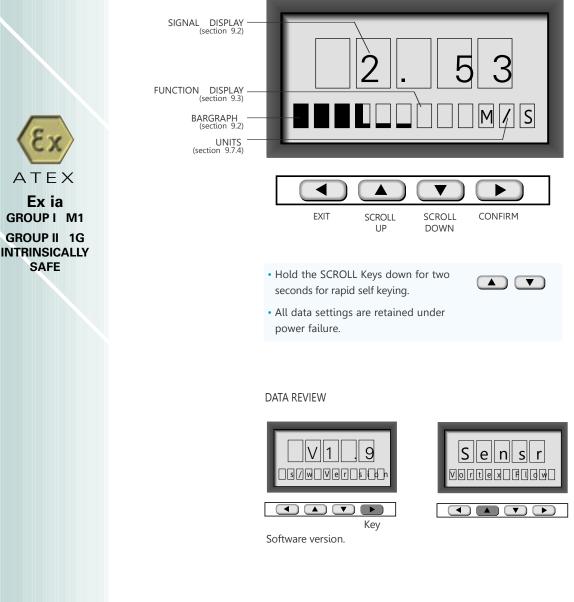




7 CONNECTORS AND INDICATORS

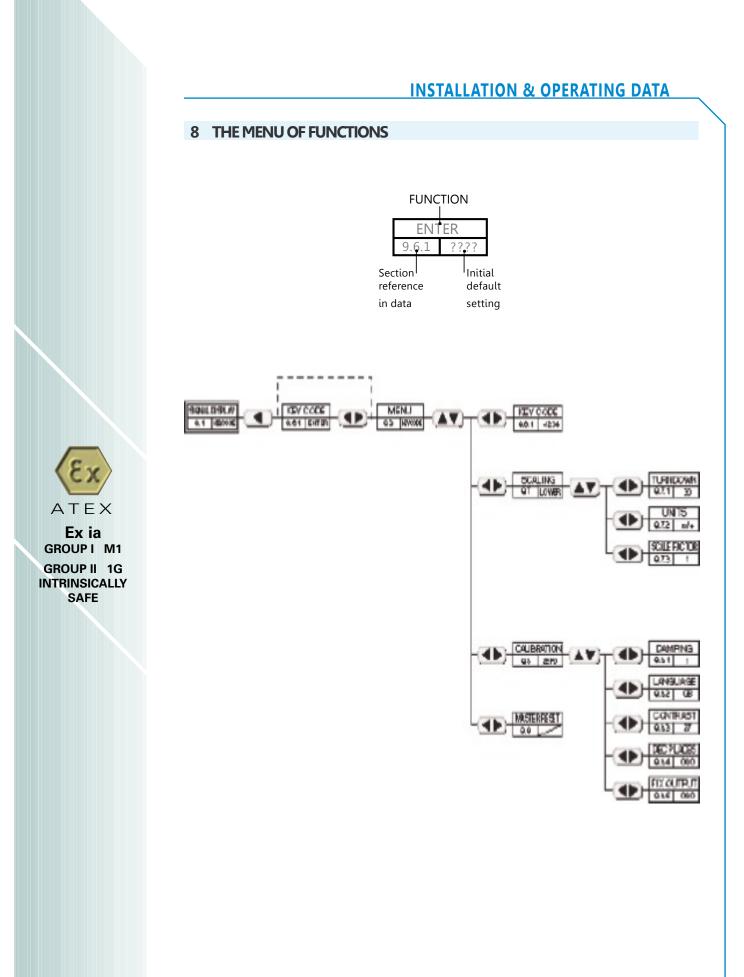
The programming and setting routines for the sensor have been designed for utmost simplicity and the programming system is completely menu driven. There is no special software programme and data input terminal and or PC is not required.

There are just four keys for controlling the complete operation and the digital display provides instructions throughout the programming process. All entries are verified in the display.



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9 PROGRAMMING AND CALIBRATION



9.1 Switching On.

When switched on, the processor will initialise all the default values unless new values have previously been programmed.

9.2 Signal Display.

After two seconds, the display will switch to the SIGNAL DISPLAY mode, showing the measured signal value with the selected engineering

units (m/s).

- The bargraph will also show a magnitude comparison of the input signal level.
- Signal over range.

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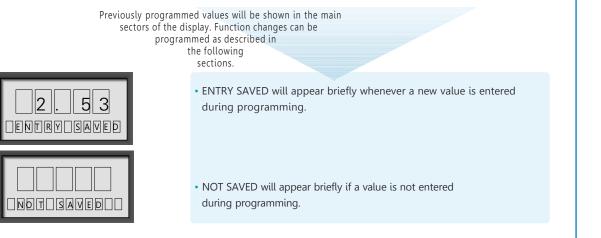


9.3 Entering the MENU.

All the operating functions of the sensor can be programmed by entering into the MAIN MENU.

- Key (to ENTER the main menu.
- Key or voice to SCROLL up and down the MENU
- Key **b** to CONFIRM.
- A request to enter a KEYCODE will appear if access

is prevented.



Refer to Section9.6



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9 PROGRAMMING AND CALIBRATION continued 9.4 Exit Key **(to** EXIT from any position in the MENU sequence. Each operation of the key will revert the display one step back in the MENU table until the SIGNAL DISPLAY is reached. 9.5 Self Test The processor will constantly carry-out a self-test routine of the main circuit elements; EPROM, memory, comms and display read/write function. Any malfunction registered will be denoted by a FAIL message in the display. Keycode 9.6 Enter a four digit security keycode to access the MAIN MENU. GROUP I M1 **GROUP II 1G** 9.6.1 Enter Keycode **INTRINSICALLY** Key **v** to TRAVERSE the cursor. Key () to INCREMENT the digit with the cursor under. Key **I** to CONFIRM. GO or NO GO will appear briefly to confirm keycode status. This request will not appear if the KEYCODE is not active. Refer to Section 9.6.2 9.6.2 Set Keycode The keycode is a selectable option and the code can be changed at any time. 3 4 The keycode can also be set to be ACTIVE or NOT ACTIVE. Key **v** to TRAVERSE the cursor. Code E n Key (to INCREMENT the digit with the cursor under. NOT ACTIVE (unrestricted access) Key **b** to CONFIRM. + ACTIVE



9 PROGRAMMING AND CALIBRATION continued

9.7 Scaling



20mA

20mA

30m/s

The numerical values presented on the display can be programmed. Key () or () to SELECT the function.

Key **I** to CONFIRM.



$\begin{array}{c} 1 5 .00 \\ 3 0 .00 \\ \end{array}$

15m/s

Adjustable Range: 5...30m/sec (16.4...98.43 ft/sec).

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9.7.1 Turndown

When the sensor is being used on a lower operating velocity range below the standard calibrated range of 0...30m/s (eg. 0...15m/s) the complete response range of the output signal can be utilised by 'Turning Down' the sensor response to the required maximum flow range of the system being monitored.

Key 💽 to TRAVERSE the cursor.

Key (to INCREMENT the digit with the cursor under.

Key **b** to CONFIRM.

9.7.2 Units

There is a choice of six engineering units of flow:-

Flow velocity values independent of the cross-sectional area of the flow path. 1.m/s (metres per second). 2.ft/s (feet per second).

Volumetric flow values relative to the cross-sectional areas of the flow path. 3.m³/s (cubic metres per second).

 $4.m^3/h$ (cubic metres per hour).

5.ft³/s (cubic feet per second).

6.ft³/h (cubic feet per hour).

- All display values will be automatically presented in the engineering units selected.
- If one of the VOLUMETRIC flow units (3 to 6) is selected, it will be necessary to enter an appropriate multiplication factor

relating to the cross-sectional area of the flow path. Refer to Section 9.7.3

Key \frown or \bigtriangledown to SELECT the UNITS.





9 PROGRAMMING AND CALIBRATION continued

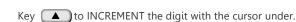
9.7.3 Scale Factor



The cross-sectional area factor MUST be entered in the relating to the cross-sectional area of the flow path. Key **T** to TRAVERSE the cursor.

If one of the four VOLUMETRIC flow units is selected, it will be necessary to enter a multiplication factor

Refer to Section9.7.2





11001 50 01	neered an and		
same dimensional units. Unit Cross-sectional area			
m³/s	square metres (m ²)		
m³/h	square metres (m ²)		
ft³/s	square feet (ft ²)		
ft³/h	square feet (ft ²)		

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9.8 Calibration

The output signal parameters and operating functions can be programmed.

Key 🚺 or 💌 to SCROLL the menu.



9.8.1 Damping

The immediacy of response of the sensor can be DAMPED to filter unwanted spurious changes in the process flow.



 to INCREMENT the digit with the cursor under. Key 🦷

Key **b** to CONFIRM.

The value entered approximates to the time taken in seconds for the signal to reach 63% of the final value (ie. one time constant).

Set Damping

Range: 0...999.9s



9 PROGRAMMING AND CALIBRATION continued

9.8.2 Language

В

Language

The display text can be shown in four different languages.



Key or to SELECT.

Key **I** to CONFIRM.



le It

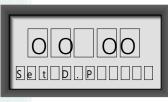
9.8.3 Contrast

The contrast of the LCD can be varied to compensate for the effect of ambient temperature and light conditions.



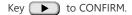
Key **b** to CONFIRM.

9.8.4 Decimal Places



Range: 0.000...00000

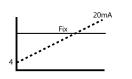
When the sensor is measuring a rapidly fluctuating signal, the fluttering minor digits in the display can be distracting. The position of the decimal point can be moved to any position in the figure to minimise this effect. Key () or () to TRAVERSE the decimal point.





9 PROGRAMMING AND CALIBRATION continued

9.8.5 Fix Output



It may be necessary, from time to time, to temporarily shut down the process to carry out maintenance or servicing which will probably mean stopping the flow.

To prevent an alarm condition being transmitted by the sensor, the output signal can be temporarily FIXED at any desired PERCENTAGE value of the

output signal range.

The FIXED LEVEL selected is a calibrated value so this feature can also be used to test the integrity of the signal loop and any remote monitoring

equipment, by simulating an output signal of defined value. Remote display systems can be calibrated and any alarm set point levels can be checked for function and accuracy.

Key 💽 to TRAVERSE the cursor.

Key **INCREMENT** the value of the digit with the cursor under.

Key 🕩 to CONFIRM.

The signal will be RELEASED when the MENU position is vacated.

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Set O/PSi

Range: 0...99.99%



9.9 Master Reset

All data will be re-initialised as if the power had been removed. All user settings will be retained.

Refer to Section 8

Key **b** to RESET.

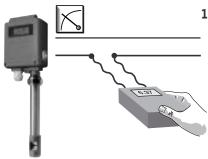
The display will return to the SIGNAL DISPLAY mode.



10 MAINTENANCE continued

There are no degradable components, but it is good safety practice to carry out regular preventative

maintenance to confirm correct operation.



10.1 Output Signal

Check at regular intervals, that the value of the output signal agrees with the value of the display reading.

Refer to Section9.8



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10.2 Sensing Probe

Under normal circumstances, the calibration of the actual sensing probe will not change by any significant degree.

Check the accuracy at least once per year by comparing

the display reading with an accurately measured value of flow velocity.

Alternatively the sensor can be returned to our Product Support Department for checking and calibration.

10.3 Cleaning the Sensing Probe

Remove the sensor at regular intervals to assess its

condition. Clean the sensing head with a soft brush

or cloth if necessary. Do not use sharp tools as this may

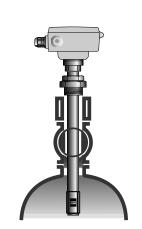
cause damage to the ultrasound transducers and

the transverse strut.

10.4 Hot Tap Mounting

Where the process cannot be interrupted to remove the sensor from a pipeline, an isolating ball valve may be

fitted to the process connection at the installation stage.





11 APPROVALS AND CERTIFICATION

11.1 Europe (ATEX)



Ex Certificate number:

I M1 Ex ia I Ma (-20°C \leq Ta \leq +60°C)

Sira 99ATEX2135X

ll 1G Ex ia IIC T4 Ga (-20°C \leq Ta \leq +60°C)

Specific Conditions of Use:

The only sensor that may be used with the TX5923 (remote sensor head version) is that provided by Trolex. The maximum length of cable allowed is 10 m.

The user should ensure that the equipment is not installed in a location where it may be subject to external conditions (such as high-pressure steam) which might cause a build-up of static on non-conducting surfaces (polycarbonate window). Additionally cleaning of the equipment should only be done with a damp cloth.

General Conditions of Use:

Prior to installation, it is essential that user refers to the above certificate to ensure that the termination and cable parameters are fully complied with and are compatible with the application. Copies of certificates are available from Trolex.

CE ATEX Directive (94/9/EC) EMC Directive (2004/108/EC)

11.2 Australia (ANZEx)

ANZE

Ex Certificate number: Ex Certification Code:

ANZEx 12.3003X Ex ia I (-20°C \leq Ta \leq +60°C) Ex ia IIC T4 (-20°C \leq Ta \leq +60°C)

Conditions of Certification:

Prior to installation, it is essential that the user refers to the above certificate to ensure that the termination and cable parameters are fully complied with and are compatible with the application. Copies of certificates are available from Trolex.

The user should ensure that the equipment is not installed in a location where it may be subject to external conditions (such as high-pressure steam) which might cause a build-up of static on non-conducting surfaces (polycarbonate window). Additionally cleaning of the equipment should only be done with a damp cloth.

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11 APPROVALS AND CERTIFICATION continued

11.3 Russia (GOST-R)



POCC GB.ME92.B02878 PO Ex ia I X

0 Ex ia IIC T4 X

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Conditions of Use:

Prior to installation, it is essential that user refers to the above certificate for any specific conditions of use. The user must ensure that the termination and cable parameters are fully complied with and are compatible with the application. Copies of certificates are available from Trolex.

11.4 South Africa



Ex certificate number:MASC MS/13-188XEx certification codes:Ex ia I (-20°C \leq Ta \leq +60°C)Ex ia IIC T4 (-20°C \leq Ta \leq +60°C)

Special Conditions of Use:

Prior to installation, it is essential that the user refers to the above certificate to ensure that the termination and cable parameters are fully complied with and are compatible with the application. Copies of certificates are available from Trolex.

The user should ensure that the equipment is not installed in a location where it may be subject to external conditions (such as high-pressure steam) which might cause a build-up of static on non-conducting surfaces (polycarbonate window). Additionally cleaning of the equipment should only be done with a damp cloth.

General Conditions of Use:

Prior to installation, it is essential that user refers to the above certificate to ensure that the termination and cable parameters are fully complied with and are compatible with the application. Copies of certificates are available from Trolex.

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